

RLC SUMMARY

I. Summary of RLC

A. Initial/ final values – short L, open C and: $v_C(0^+) = v_C(0^-)$ $i_L(0^+) = i_L(0^-)$

1. For derivatives: \dot{v}, i' use $i_C = C\dot{v}$ and $v_L = Li'$

II. SOURCE FREE

Σ RLC

// RLC

$$i'' + (R/L)i' + (1/LC)i = 0 \text{ (KVL)}$$

$$\ddot{v} + (1/RC)\dot{v} + (1/LC)v = 0$$

$$\text{(alt) } \ddot{v}_C + (R/L)\dot{v}_C + (1/LC)v_C = 0$$

$$\text{(alt) } i_L'' + (1/RC)i_L' + (1/LC)i_L = 0$$

$$s^2 + 2\alpha s + \omega_o^2 = 0$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_o^2}$$

$$\alpha = R/(2L); \omega_o = 1/\sqrt{LC}$$

$$\alpha = 1/(2RC); \omega_o = 1/\sqrt{LC}$$

Solutions

$\alpha > \omega_o$ (overd) $s_{1,2}$ real, (-), distinct

$$i(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$v(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$\alpha = \omega_o$ (crit) $s_{1,2}$ real, (-), equal

$$i(t) = e^{-\alpha t} (A_2 + A_1 t)$$

$$v(t) = e^{-\alpha t} (A_2 + A_1 t)$$

$\alpha < \omega_o$ (underd) $s_{1,2}$ complex, distinct

$$i(t) = e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t)$$

$$v(t) = e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t)$$

$$\omega_d = \sqrt{\omega_o^2 - \alpha^2}$$

BCs

$$i(0) = I_o$$

BCs

$$V_o$$

$$i'(0) = -(RI_o + V_o)/L$$

$$\dot{v}(0) = -(V_o + I_o R)/(RC)$$

$$\text{OR } i'(0) = v_o / L \text{ (for i eqn)}$$

STEP RESPONSE

Σ RLC (step w/ VS), $v = v_C$

// RLC (step with CS, $i = i_L$)

$$\ddot{v} + (R/L)\dot{v} + (1/LC)v = V_S(1/LC)$$

$$i_L'' + (1/RC)i_L' + (1/LC)i_L = I_S(1/LC)$$

$$\text{(alt) } i'' + (R/L)i' + (1/LC)i = 0$$

$$\text{(alt) } \ddot{v} + (1/RC)\dot{v} + (1/LC)v = 0$$

Step Solns

$$v_C(t) = V_S + A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

Step Solns

$$i(t) = I_S + A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$v(t) = V_S + (A_1 + A_2 t) e^{-\alpha t}$$

$$i(t) = I_S + (A_1 + A_2 t) e^{-\alpha t}$$

$$v(t) = V_S + e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t)$$

$$i(t) = I_S + e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t)$$

$$\alpha = R/(2L); \omega_o = 1/\sqrt{LC}$$

$$\alpha = 1/(2RC); \omega_o = 1/\sqrt{LC}$$

Diff Eq's are now NON-homogeneous. Solutions have a transient (homogeneous) and steady-state component (particular). The transient solution is associated with the source-free response. The steady-state is associated with the "driving" element (VS or CS).

$$\begin{array}{ll}
 v(t) = v_{ss} + v_t & i(t) = i_{ss} + i_t \\
 v(t) = V_S + A_1 e^{s_1 t} + A_2 e^{s_2 t} & i(t) = I_S + A_1 e^{s_1 t} + A_2 e^{s_2 t} \quad (\text{over}) \\
 v(t) = V_S + e^{-\alpha t} (A_1 + A_2 t) & i(t) = I_S + e^{-\alpha t} (A_1 + A_2 t) \quad (\text{crit}) \\
 v(t) = V_S + e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t) & i(t) = I_S + e^{-\alpha t} (A_1 \cos \omega_d t + A_2 \sin \omega_d t) \quad (\text{under})
 \end{array}$$

III. Solving problems

- A. Get initial values: $i(0^-)$, $v(0^-)$ (short L, open C, do analysis as usual)
- B. Get values $t = 0^+$ (just after event).
 1. $i_L(0^+) = i_L(0^-)$ (i on L contin.)
 2. $v_C(0^+) = v_C(0^-)$ (v on C contin)
 3. $i'(0^+) \leftarrow v'(0^+) = v_L(0^+)/L$ (get via voltage across L)
 4. $\dot{v}(0^+) \leftarrow \dot{v}(0^+) = i_C(0^+)/C$ (get via current thru C)
- C. Get transient response
 1. Get α & ω_o (depends on circuit, series, parallel, etc.)
 2. Is it over, under, or critically damped?
 3. Compute roots s_1 & s_2 .
 4. Pick proper equation (based on damping)
 5. Get A_1 & A_2 from BC's.
 - a. For source-free series RLC we want $i(0^+), i'(0^+)$
 - b. For source-free parallel RLC we want: $v(0^+), \dot{v}(0^+)$
 - c. For step-response series RLC we want $v(0^+), \dot{v}(0^+)$
 - d. For step-response parallel RLC we want $i(0^+), i'(0^+)$
- D. Get final response ($t = \infty$) – just like $t < 0$
 1. Note – steady state response of source-free is always = 0 (no source, decays to 0)
 2. Step response variable is opposite to source-free (v for series RLC, I for // RLC) (it STEPS)

IV. Solving GENERAL second order circuits (SKIP FOR NOW)

- A. Get initial conditions: $x(0)$, $\dot{x}(0)$, and final conditions $x(\infty)$
- B. Get transient response $x_t(t)$
 1. Turn off independent sources
 2. Use KCL or KVL.
 3. Get s_1, s_2
 4. Get damping type (under, critically, over damped).
 5. Get A_1 & A_2 from BCs.
- C. Get steady state response $x_{ss} = x(\infty)$
- D. Get total response $x(t) = x_t(t) + x_{ss}(t)$